LIST OF FORMULAS FOR MATH 113, FALL 2012, PART 2

- The level curves of a function f of two variables are the curves with equations f(x, y) = k, where k is constant.
- The limit of f(x, y) as (x, y) approaches (a, b) is L and we write

$$\lim_{(x,y)\to(a,b)} f(x,y) = L$$

if for every number $\varepsilon > 0$ there is a corresponding number $\delta > 0$ such that if $(x, y) \in D$ and $0 < \sqrt{(x-a)^2 + (y-b)^2} < \delta$ then $|f(x, y) - L| < \varepsilon$. We also write $f(x, y) \to L$.

- If $f(x,y) \to L_1$ as $(x,y) \to (a,b)$ along a path C_1 and $f(x,y) \to L_2$ as $(x,y) \to (a,b)$ along a path C_2 , where $L_1 \neq L_2$, then $\lim_{(x,y)\to(a,b)} f(x,y)$ does not exist.
- A function f of two variables is called **continuous at** (a, b) if $\lim_{(x,y)\to(a,b)} f(x,y) = f(a,b)$.
- The partial derivatives are defined via

$$f_x(a,b) = \lim_{h \to 0} \frac{f(a+h,b) - f(a,b)}{h}$$
$$f_y(a,b) = \lim_{h \to 0} \frac{f(a,b+h) - f(a,b)}{h}$$

- To find f_x regard y as a constant and differentiate f(x, y) with respect to x.
- To find f_y regard x as a constant and differentiate f(x, y) with respect to y.
- An equation of the tangent plane to the surface z = f(x, y) at the point $P(x_0, y_0, z_0)$ is

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

• The linear function whose graph is this tangent plane

$$L(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

is called the **linearization** of f at (a, b)

• The approximation

$$f(x,y) \approx f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

is called the **linear approximation** or the **tangent plane approximation** of f at (a, b).

• If z = f(x, y) and x changes from (a, b) to $(a + \Delta x, b + \Delta y)$, then the **increment** of z is

$$\Delta z = f(a + \Delta x, b + \Delta y) - f(a, b)$$

• If z = f(x, y), then f is **differentiable** at (a, b) if Δz can be expressed in the form

$$\Delta z = f_x(a,b)\Delta x + f_y(a,b)\Delta y + \epsilon_1\Delta x + \epsilon_2\Delta y,$$

where ϵ_1 and $\epsilon_2 \to 0$ as $(\Delta x, \Delta y) \to (0, 0)$.

• For a differentiable function z = f(x, y) we define the **differential** dz, also called the **total differential**, is defined by

$$dz = f_x(x, y)dx + f_y(x, y)dy = \frac{\partial z}{\partial x}dx + \frac{\partial z}{\partial y}dy$$

where the **differentials** dx and dy are independent variables.

• If $dx = \Delta x = x - a$ and $dy = \Delta y = y - b$ the the differential of z is

$$dz = f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

• Chain Rule, case 1: Suppose that z = f(x, y) is a differentiable function of x and y, where x = g(t) and y = h(t) are both differentiable functions of t. Then z is a differentiable function of t and

$$\frac{\mathrm{d}z}{\mathrm{d}t} = \frac{\partial f}{\partial x}\frac{\mathrm{d}x}{\mathrm{d}t} + \frac{\partial f}{\partial y}\frac{\mathrm{d}y}{\mathrm{d}t}.$$

• Chain Rule, case 2: Suppose t hat z = f(x, y) is a differentiable function of x and y, where x = g(s, t) and y = h(s, t) are differentiable functions of s and t. Then

$\frac{\partial z}{\partial z}$	_	$\frac{\partial z}{\partial x} \frac{\partial x}{\partial x}$	$\perp \frac{\partial z}{\partial y}$
∂s	_	$\partial x \ \partial s$	$dy \ \partial s$
∂z	=	$\partial z \ \partial x$	$\partial z \partial y$
∂t		$\overline{\partial x} \ \overline{\partial t}$	$+ \overline{\partial y} \overline{\partial t}$

• The directional derivative of f at (x_0, y_0) in the direction of a unit vector $\mathbf{u} = \langle a, b \rangle$ is

$$D_{\mathbf{u}}f(x_0, y_0) = \lim_{h \to 0} \frac{f(x_0 + ha, y_0 + hb) - f(x_0, y_0)}{h}$$

if this limit exists.

• If f is a differentiable function of x and y, then f has a directional derivative in the direction of any unit vector $\mathbf{u} = \langle a, b \rangle$ and

$$D_{\mathbf{u}}f(x,y) = f_x(x,y)a + f_y(x,y)b.$$

• If the unit vector **u** makes an angle θ with the positive x-axis, then we can write $\mathbf{u} = \langle \cos \theta, \sin \theta \rangle$ and

$$D_{\mathbf{u}}f(x,y) = f_x(x,y)\cos\theta + f_y(x,y)\sin\theta$$

• If f is a function of two variables x and y, then the **gradient** of f is the vector function ∇f defined by

$$\nabla f(x,y) = \langle f_x(x,y), f_y(x,y) \rangle = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j}.$$

- The tangent plane to the level surface F(x, y, z) = k at $P(x_0, y_0, z_0)$ is the plane passes through P and has normal vector $\nabla F(x_0, y_0, z_0)$.
- The **normal line** to *S* at *P* is the line passing through *P* and perpendicular to the tangent plane.
- A function f has a **local maximum** at (a, b) if

$$f(x,y) \le f(a,b)$$

when (x, y) is near (a, b). The number f(a, b) is called a **local maximum** value.

• A function f has a **local minimum** at (a, b) if

$$f(x,y) \ge f(a,b)$$

when (x, y) is near (a, b) and f(a, b) is called a **local minimum value**. • If

 $f(x,y) \le f(a,b)$

(or $f(x, y) \ge f(a, b)$) for all points (x, y) in the domain of f, then f has an **absolute maximum** (or **absolute minimum**) at (a, b).

- A point (a,b) is called a **critical point** (or **stationary point**) of f if $f_x(a,b) = 0$ and $f_y(a,b) = 0$.
- Second Derivative Test: Suppose the second partial derivatives of f are continuous on a disk with center (a, b), and suppose that $f_x(a, b) = 0$ and $f_y(a, b) = 0$. Let

$$D = \left| \begin{array}{cc} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{array} \right| = f_{xx} f_{yy} - (f_{xy})^2.$$

- (1) If D > 0 and $f_{xx}(a, b) > 0$, then f(a, b) is a local minimum.
- (2) If D > 0 and $f_{xx}(a, b) < 0$, then f(a, b) is a local maximum.
- (3) If D < 0, then f(a, b) is not a local maximum or minimum. In this case the point (a, b) is called a saddle point of f.