Definition

The *transpose* A^T of the matrix A is the result of turning the rows into columns and vice versa:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^{\mathsf{T}} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Notes:

- (A + B)^T = A^T + B^T.
 (cA)^T = cA^T.
 (AB)^T = B^TA^T. (So (A⁻¹)^T = (A^T)⁻¹.)
 If A^T = A, then A is symmetric (and square).
- v ⋅ w = v^Tw (the last a product as matrices, so that the resulting 1 × 1 matrix is just a number).

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Example

If A and B are symmetric (of the same size), must AB - BA be symmetric? Well,

$$(AB - BA)^{T} = (AB)^{T} - (BA)^{T} = B^{T}A^{T} - A^{T}B^{T} = BA - AB$$
.

This is the negative of the original difference matrix, so unless AB = BA (i.e., the original matrix is all 0's), AB - BA cannot be symmetric.

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Example

If A and B are symmetric (of the same size), must ABAB be symmetric? Well,

$$(ABAB)^{T} = B^{T}A^{T}B^{T}A^{T} = BABA .$$

This doesn't look the same as *ABAB*, but it may be; for example, $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$:

$$AB = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \qquad BA = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

have $ABAB = -I_2 = BABA$. But the same A and $B = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$ doesn't work:

$$ABAB = \begin{bmatrix} 8 & 16 \\ 4 & 8 \end{bmatrix}$$
 (not symmetric).

Uniqueness of LDU decomposition

The text says that if A has two LDU decompositions, they must be the same. Let's show that's true if A has all nonzero pivots: Suppose $L_1D_1U_1 = L_2D_2U_2$, where the L's, D's and U's have the usual properties — and all the entries on the main diagonal of D_1 are nonzero. Then

 $L_2^{-1}L_1D_1 = D_2U_2U_1^{-1} .$

The left side is all 0's above the main diagonal, the right side is all 0's below it; so both sides are diagonal; and the main diagonal entries on both sides agree, so we have $D_1 = D_2$. Now suppose $L_2^{-1}L_1$ has a nonzero entry off the main diagonal; then the left side has a nonzero entry below the main diagonal, so the same is true of the right side, a contradiction. So $L_2^{-1}L_1$ is diagonal, and because both *L*'s have 1's on the main diagonal, the product is the identity, i.e., $L_1 = L_2$. Similarly for the other side, so $U_1 = U_2$ also.

Nonuniqueness of LDU decomposition

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & x & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} ,$

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no matter what x is.

LU Decomposition in Matlab

>> A = [1 3 5 ; 2 4 6 ; 5 5 2]]
A =	U =
1 3 5	5.0000 5.0000 2.0000
2 4 6	0 2.0000 5.2000
552	0 0 -0.6000
>> lu(A)	P =
ans =	0 0 1
5.0000 5.0000 2.0000	0 1 0
0.4000 2.0000 5.2000	1 0 0
0.2000 1.0000 -0.6000	>> P*A-L*U
>> [L,U,P] = Iu(A)	ans =
	0 0 0
1.0000 0 0	0 0 0
0.4000 1.0000 0	0 0 0
0.2000 1.0000 1.0000	

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LU Decomposition in R

```
> library(Matrix)
> A < -matrix(c(1,3,5,2,4,6,5,5,2), nrow=3, byrow=TRUE)
> lu(A)
'MatrixFactorization' of Formal class 'denseLU' [package "Matrix"]
with 3 slots
..@ x : num [1:9] 5 0.4 0.2 5 2 ...
..@ perm : int [1:3] 3 2 3
..@ Dim : int [1:2] 3 3
```

(continued)

```
> F < - expand(lu(A))
> F
3 \times 3 Matrix of class "dtrMatrix" (unitriangular)
        [; 1] [; 2] [; 3]
   [1;]
       1.0
            .
   [2;] 0.4 1.0 .
   [3;] 0.2 1.0 1.0
> F
3 x 3 Matrix of class "dtrMatrix"
        [; 1] [; 2] [; 3]
   [1; ]
       5.0 5.0 2.0
   [2; ]
      . 2.0 5.2
   [3; ]
       . . -0.6
```

(continued again)

> F\$P 3 x 3 sparse Matrix of class "pMatrix" [1;] . . | [2;] . | . [3;] . . > F\$P% * %A-F\$L% * %F\$U 3 x 3 Matrix of class "dgeMatrix" [; 1] [; 2] [; 3] [1;] 0 0 0 [2;] 0 0 0 0 [3;] 0 0