

Matrices:

Definition of: $\Rightarrow$ a short hand notation $\Leftarrow$

$$\begin{array}{l} 2x + 3y = 5 \\ 4x - 6y = 3 \end{array} \Leftrightarrow \underbrace{\begin{bmatrix} 2 & 3 \\ 4 & -6 \end{bmatrix}}_{\underline{A}} \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_{\underline{x}} = \underbrace{\begin{bmatrix} 5 \\ 3 \end{bmatrix}}_{\underline{b}} \Leftrightarrow \underline{A} \underline{x} = \underline{b}$$

In general,

$$\begin{array}{l} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{array} \Leftrightarrow \underline{A} \underline{x} = \underline{b}$$

Multiplication, Addition, etc. Size: $\underline{A}$ is an "m by n" matrix if it has m rows and n columns

Matrices can be added or subtracted if they are the same size. Just add components.

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} + \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = \begin{bmatrix} 3 & 5 \\ 7 & 9 \end{bmatrix}$$

Matrix multiplication is like a dot product: $\begin{bmatrix} 1 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \end{bmatrix} = [1 \cdot 2 + 3 \cdot 4] = [14] =$

$$\underbrace{\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}}_{\underline{A}} \underbrace{\begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}}_{\underline{B}} = \begin{bmatrix} 2+8 & 3+10 \\ 6+16 & 9+20 \end{bmatrix} = \begin{bmatrix} 10 & 13 \\ 22 & 29 \end{bmatrix}$$

1 by 1 matrix
is a number

To find the i^{th} row, j^{th} column of the product take dot product of the i^{th} row with the j^{th} column.

WARNING $\underline{A} \cdot \underline{B}$ is not $\underline{B} \cdot \underline{A}$ most of the time. ORDER MATTERS

So division cannot use fraction notation! We must keep the order intact.

Division: Note: $\underline{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ is a matrix with ones on the main diagonal and zeros off this diagonal. It is called the Identity matrix because $\underline{A} \underline{I} = \underline{A}$ for all $\underline{A}$

to solve $\underline{A} \underline{x} = \underline{b}$ for $\underline{x}$, we just divide by $\underline{A}$ on the left. We write that as multiplying by $\underline{A}^{-1}$

$$\underline{A}^{-1} \underline{A} \underline{x} = \underline{A}^{-1} \underline{b} \quad \text{To have this work as division, it must be that } \underline{A}^{-1} \underline{A} = \underline{I}$$

Define: $\underline{A}^{-1}$ to be the matrix such that $\underline{A}^{-1} \underline{A} = \underline{I}$ for a given $\underline{A}$.

WARNING: Just as we cannot divide by zero, the inverse may not exist!!

The determinant of $\underline{A}$ tells you if the inverse exists. $\det(\underline{A}) \neq 0$ means $\underline{A}$ has an inverse (is invertible).

Determinants: This is an operation that takes a matrix and gives a single number.

2x2 (2 by 2) matrices:

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc. \quad \left(\begin{array}{l} \text{multiply the diagonal elements} \\ \text{and subtract the product of off} \\ \text{diagonal elements} \end{array} \right)$$

3x3 matrices:

$$\det \begin{bmatrix} \oplus a & \ominus b & \oplus c \\ d & e & f \\ g & h & i \end{bmatrix} = a \cdot \det \begin{bmatrix} e & f \\ h & i \end{bmatrix} - b \det \begin{bmatrix} d & f \\ g & i \end{bmatrix} + c \det \begin{bmatrix} d & e \\ g & h \end{bmatrix} \\ = aei - afh - bdi + bfg + cdh - ceg$$

Larger matrices are similarly defined in terms of smaller determinants:

n x n matrices:

$$\det(\underline{A}) = a_{11} \cdot \det(\underline{A} \text{ with row 1 and column 1 removed}) - a_{12} \cdot \det(\underline{A} \text{ with row 1 and column 2 removed}) + a_{13} \cdot \det(\underline{A} \text{ with row 1 and column 3 removed}) \\ \ominus \dots \pm a_{1n} \det(\underline{A} \text{ with row 1 and column n removed})$$

↑
minus if n odd,
plus if n even.

Trace: The trace of $\underline{A}$ is just the sum of the main diagonal.

$$\text{tr} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = 1 + 5 + 9 = 15$$

Eigen values, eigenvectors: An eigenvalue problem for $\underline{A}$ involves finding a solution pair $(\lambda, \underline{u})$ such that $\boxed{\underline{A}\underline{u} = \lambda\underline{u}}$

Note: If $\underline{A}$ is $n \times n$ then $\underline{u}$ is $n \times 1$ so we have $n+1$ unknowns with n equations.

First find eigenvalues: solve $\underline{A}\underline{u} - \lambda\underline{u} = \underline{0}$

$$(\underline{A} - \lambda \underline{I})\underline{u} = \underline{0} \quad \text{but the solution } \underline{u} \text{ will be zero unless the inverse of } (\underline{A} - \lambda \underline{I}) \text{ does not exist.}$$

Choose λ so that $\det(\underline{A} - \lambda \underline{I}) = 0$.

Then $\underline{u}$ can be non-zero.

Second: find eigenvectors: for each λ , plug in λ to $(\underline{A} - \lambda \underline{I})\underline{u} = \underline{0}$ and then solve for $\underline{u}$.

Note: any multiple of $\underline{u}$ is also an eigenvector, so you can set one element of $\underline{u}$ to be a convenient non-zero value like 1.

Example: $\underline{A} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$; $\det(\underline{A} - \lambda \underline{I}) = \det \begin{bmatrix} 1-\lambda & 2 \\ 3 & 4-\lambda \end{bmatrix} = (1-\lambda)(4-\lambda) - 6 = \lambda^2 - 5\lambda - 2$ we find the roots $\lambda_{1,2} = \frac{5 \pm \sqrt{25+8}}{2}$

$\lambda = \frac{5}{2} + \frac{\sqrt{33}}{2} \Rightarrow$ find $\underline{u}$ $\begin{bmatrix} -\frac{3}{2} - \frac{\sqrt{33}}{2} & 2 \\ 3 & \frac{3}{2} - \frac{\sqrt{33}}{2} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ so $\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 2 \\ \frac{3+\sqrt{33}}{2} \end{bmatrix}$ works as an eigenvector for the eigenvalue $\frac{5}{2} + \frac{\sqrt{33}}{2}$