Math 308

Pendulum without friction.
> with (plots):
Warning, the name changecoords has been redefined
We saw in class that the trajectories in the phase plane are contour lines of the following function.
$>\mathrm{H}:=\mathrm{y}^{\wedge} 2 / 2-\cos (\mathrm{x})$;

$$
H:=\frac{1}{2} y^{2}-\cos (x)
$$

$>$ plot $3 \mathrm{~d}(\mathrm{H}, \mathrm{x}=-4 . .8, \mathrm{y}=-2.3 .2 .3$, style=patchcontour, orientation=[-40,7 $0]$, axes=boxed, shading=zgrayscale, contours $=[-0.95,-.5,0, .5,1,1.5,2]$ ) ;

$>$ contourplot $(\mathrm{H}, \mathrm{x}=-4 . \mathrm{B}, \mathrm{y}=-2.3 \mathrm{~m} .3$, contours $=[-0.95,-.5,0,0.5,1,1.5$, 2], grid=[101, 101], color=black, thickness=2) ;

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